X-ray scattering factor for $\mathrm{NH}_{4}^{+}$at rest from the observed radial scattering factors $f_{0}, f_{4}$. Such a result yields, however, only the qualitative conclusion, already reached in the X-ray analysis, that the one-centre SCF calculations do not give large enough non-spherical components, i.e., they do not yield a sharp enough concentration of charge around the hydrogen atoms. Observations on another dynamical state (e.g. temperature variation, isotopic replacement $\mathrm{ND}_{4}$ ) would give, at least in principle, complementary information on the physical basis of this deviation. Such studies would gain substantially from theoretical scattering factors of free $\mathrm{NH}_{4}^{+}$, with the observed bond length and with some internal dynamics included to account for the observed average bond vibrations. The anisotropy of chlorine vibrations is, in any case, far too small to cause observable effects in the X-ray scattering factor of chlorine.

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# Restriction of the Number of Terms in the Sayre-Hughes Equation Connected with a Criterion to Establish the Absence of Atomic Overlap in Projection 

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#### Abstract

In the Sayre-Hughes equation the variable reciprocal-lattice vector ranges over the whole reciprocal net. It is shown that under the condition that a projection along a zone axis has no overlapping atoms the variable reciprocal-lattice vector can be restricted to range over a plane of the reciprocal net. $A$ fortiori if a projection on an axis is free from overlap the variable vector can be restricted to range over a row of the reciprocal net. Criteria to determine the projections for which these conditions are best fulfilled are given. These criteria involve the absolute values of the structure factors only. The theory is illustrated by a test employing normalized structure factors calculated from atomic coordinates.


## Introduction

It is always possible to determine the three-dimensional structure from any two resolved two-dimensional projections for which the projection on their intersecting line is resolved. In the case that only one two-
dimensional projection is resolved use can be made of generalized projections to find the three-dimensional structure.

For reciprocal space it follows that under the conditions mentioned above, a restricted number of structure factors determines the others (at the given
resolution). In this paper we shall first show that under these circumstances the number of terms in the Sayre-Hughes equation can be restricted. The resulting equations will be called reduced SayreHughes equations. Secondly we shall show how to find those projections for which the conditions of no atomic overlap are best fulfilled. Only the absolute values of structure factors enter into this procedure.

## Reduced Sayre-Hughes equations

Denote by $N$ the number of atoms in the unit cell, by $Z_{j}$ the number of electrons of atom $j$, and define

$$
\begin{equation*}
\sigma_{n}=\sum_{j=1}^{N} Z_{j}^{n} \tag{1}
\end{equation*}
$$

Define the normalized structure factor $E_{\mathrm{h}}$ and the normalized structure factor of the squared structure $E_{\mathbf{h}}^{s}$ by

$$
\begin{equation*}
E_{\mathbf{h}}=\sum_{j=1}^{N} \frac{Z_{j}}{\sigma_{2}^{1 / 2}} \exp 2 \pi i \mathbf{h} \cdot \mathbf{r}_{j} \tag{2}
\end{equation*}
$$

and

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\sum_{j=1}^{N} \frac{Z_{j}^{2}}{\sigma_{4}^{1 / 2}} \exp 2 \pi i \mathbf{h} \cdot \mathbf{r}_{j} \tag{3}
\end{equation*}
$$

respectively.
With these definitions the Sayre-Hughes equation (Sayre, 1952; Hughes, 1953) is written as

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{\mathbf{k}} \tag{4}
\end{equation*}
$$

where $\mathbf{k}$ is a vector which ranges throughout the reciprocal net. We shall show that if certain conditions, to be specified below, are fulfilled, it suffices if $\mathbf{k}$ ranges over planes or rows of the reciprocal net.
(a) If there are no atoms with the same $x$ coordinate, $\delta_{x_{i} x_{j}}=\delta_{i j}, i, j=1, \ldots, N$, then

$$
\begin{align*}
\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{k_{1}} & =\frac{1}{\sigma_{2}} \sum_{i=1}^{N} \sum_{j=1}^{N} Z_{i} Z_{j} \\
& \times\left\langle\exp 2 \pi i\left[\mathbf{h} \cdot \mathbf{r}_{j}+\mathbf{k} \cdot\left(\mathbf{r}_{i}-\mathbf{r}_{j}\right)\right]\right\rangle_{k_{1}} \\
& =\frac{1}{\sigma_{2}} \sum_{i=1}^{N} \sum_{j=1}^{N} Z_{i} Z_{j}\left\{\operatorname { e x p } 2 \pi i \left[\mathbf{h} \cdot \mathbf{r}_{j}\right.\right. \\
& \left.\left.+k_{2}\left(y_{i}-y_{j}\right)+k_{3}\left(z_{i}-z_{j}\right)\right]\right\} \delta_{x_{i} x_{j}}=\frac{\sigma_{4}^{1 / 2}}{\sigma_{2}} E_{\mathbf{h}}^{s} \\
E_{\mathbf{h}}^{s} & =\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{k_{1}} \tag{5a}
\end{align*}
$$

(b) If there are no atoms with the same $(x, y)$ coordinates, $\delta_{x_{i} x_{j}} \delta_{y_{i} v_{j}}=\delta_{i j}, i, j=1, \ldots, N$, then

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{k_{1} k_{2}} \tag{6a}
\end{equation*}
$$

Equations ( $5 a$ ) and ( $6 a$ ) will be referred to as the reduced Sayre-Hughes equations.*

In (5a) $k_{2}$ and $k_{3}$ are fixed. For $k_{2}=0$ and $k_{3}=h_{3}$, only projection reflexions are needed to calculate $E_{\mathrm{h}}^{\mathrm{s}}$. If all the projection reflexions $E_{h_{1} 0 h_{3}}$ and $E_{h_{1} h_{2} 0}$ are known, all the $E_{\mathrm{h}}^{s}$ can be calculated. This means that the three-dimensional structure can be obtained from the $\mathbf{b}$ and $\mathbf{c}$ projections.
In (6a) $k_{3}$ is fixed. If all the $E_{h_{1} h_{2} 1}$ are known (then the $E_{h_{1} h_{2} \overline{1}}$ are also known) all the $E_{h_{1} h_{2} 0}^{s}$ and the $E_{h_{1} h_{2}}^{s}$ can be calculated. Next for equal-atom structures ( $E_{\mathrm{h}}^{s}=E_{\mathrm{h}}$ ), all the $E_{h_{1} h_{2}{ }^{3}}$ etc. can be calculated: the generalized projection for $k_{3}=1$ suffices to calculate the three-dimensional structure. Again for equal-atom structures it can be seen that if all the $E_{h_{1} h_{2} h_{3}}$ with $h_{3}$ fixed are known, all the $E_{h_{1} h_{2} h_{3}}$ for all integers $n$ can be calculated. For structures consisting of unequal atoms we can use

$$
\begin{equation*}
E_{\mathrm{h}}^{s} \simeq-\frac{\sigma_{3}}{\sigma_{2}^{1 / 2} \sigma_{4}^{1 / 2}}-E_{\mathrm{h}} \tag{7}
\end{equation*}
$$

(Cochran \& Woolfson, 1955). These results can be interpreted as follows. The electron density is given by

$$
\begin{equation*}
\varrho(x, y, z)=\frac{1}{c} \sum_{k_{3}} \varrho_{k_{3}}(x, y) \exp -2 \pi i k_{3} z, \tag{8}
\end{equation*}
$$

where the generalized projections $\varrho_{k_{3}}(x, y)$ along $\mathbf{c}$ are non-zero only if $(x, y)=\left(x_{j}, y_{j}\right), j=1, \ldots, N$. From the condition $\delta_{x_{i} x_{i}} \delta_{y_{i} \nu_{i}}=\delta_{i,}, i, j=1, \ldots, N$, it follows that $\varrho\left(x_{j}, y_{j}, z\right)$ is non-zero only if $z=z_{j}$. Therefore the real parts of the terms in the right-hand side of (8) with $k_{3} \neq 0$ have at least a maximum for $z=z_{j}$. For $k_{3}=0$ no information about the value for $z_{j}$ can be obtained. For $k_{3}=1$ there is only one maximum. The position of this maximum gives the value for $z_{j}$. In general the term with $k_{3} \neq 0$ has $\left|k_{3}\right|$ maxima which lead to $\left|k_{3}\right|$ possible values for $z_{j}$. Further, we note that from ( $6 a$ ) it can be shown that a generalized projection of the squared structure is proportional to the product of two generalized projections.

In considering the similarity between the modulus projections $\left|\varrho_{k_{3}}(x, y)\right|$ and the projection with $k_{3}=0$, especially when there are no atoms which overlap in the c projection, Vainshtein (1959a,b) was led to equalities which interrelate the structure factors of parallel reciprocal-lattice planes. Analogously he has found equalities which interrelate the structure factors of parallel reciprocal-lattice rows for the case that no atoms overlap in the projection on an axis. In fact his equalities can be obtained from special cases of the reduced Sayre-Hughes equations.

When ( $5 a$ ) and ( $6 a$ ) are compared with (4) it is seen that the stronger the conditions for the $\mathbf{r}_{j}$, the more the part of the reciprocal net through which $\mathbf{k}$ ranges

[^0]can be restricted. If in (5a) $k_{2}$ and $k_{3}$ are not fixed but take on a restricted number of values then the condition $\delta_{x_{i} x_{j}}=\delta_{i j}$ is relaxed. The same holds for the condition $\delta_{x_{i} x_{j}} \delta_{y_{i} y_{j}}=\delta_{i j}$ if in ( $6 a$ ) $k_{3}$ takes on a restricted number of values. We shall give an example. Assume that only atoms 1 and 2 have the same $(x, y)$ coordinates. Then
\[

$$
\begin{align*}
& \left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{\substack{k_{1} k_{2} \\
k_{3}=k_{31}, k_{32}}}=\frac{1}{\sigma_{2}} \sum_{i=1}^{N} \sum_{j=1}^{N} Z_{i} Z_{j} \\
& \quad \times\left\{\exp 2 \pi i \mathbf{h} . \mathbf{r}_{j}\right\} \delta_{x_{i} x_{j}} \delta_{y_{i} y_{j}} \\
& \quad \times\left\langle\exp 2 \pi i k_{3}\left(z_{i}-z_{j}\right)\right\rangle_{k_{3}=k_{31}, k_{32}} \\
& \quad=\frac{\sigma_{4}^{1 / 2}}{\sigma_{2}} E_{\mathbf{h}}^{s}+\frac{Z_{1} Z_{2}}{\sigma_{2}}\left\{\exp 2 \pi i\left(h_{1} x_{1}+h_{2} y_{1}\right)\right\} \\
& \quad \times\left\{\exp 2 \pi i h_{3} z_{2}\left\langle\exp 2 \pi i k_{3}\left(z_{1}-z_{2}\right)\right\rangle_{k_{3}=k_{31}, k_{32}}\right. \\
& \left.\quad+\exp 2 \pi i h_{3} z_{1}\left\langle\exp 2 \pi i k_{3}\left(z_{2}-z_{1}\right)\right\rangle_{k_{3}=k_{31}, k_{32}}\right\} \tag{9}
\end{align*}
$$
\]

If $k_{31}$ and $k_{32}$ are chosen in such a way that

$$
k_{31}\left(z_{1}-z_{2}\right)=k_{32}\left(z_{1}-z_{2}\right)+\frac{1}{2}(\bmod 1),
$$

then the result is

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{\substack{k_{1} k_{2} \\ k_{3}=k_{31}, k_{32}}} \tag{10}
\end{equation*}
$$

which should be compared with ( $6 a$ ).

## Overlap criteria

For $\mathbf{h}=\mathbf{0}$ we find from the reduced Sayre-Hughes equations

$$
\begin{equation*}
\left.\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{k_{1}}=1 \quad \text { if } \quad \delta_{x_{i} x_{j}}=\delta_{i j}, i, j=1, \ldots, N \tag{11}
\end{equation*}
$$

and

$$
\begin{equation*}
\left.\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{k_{1} k_{2}}=1 \quad \text { if } \quad \delta_{x_{t} x_{j}} \delta_{y_{i} y_{j}}=\delta_{i j}, i, j=1, \ldots, N \tag{12}
\end{equation*}
$$

Compare with

$$
\begin{equation*}
\left.\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{\mathbf{k}}=1 \tag{13}
\end{equation*}
$$

Equating the mean values in (12) for different values of $k_{3}$ a relation between the absolute values of structure factors is obtained. Vainshtein (1959a,b) has pointed out that the fulfilment of such a relation indicates the absence of atomic overlap in projection and the validity of his equalities between the structure factors of parallel reciprocal-lattice planes. It also indicates the validity of the reduced Sayre-Hughes equation ( $6 a$ ). As quantitative criteria we define

$$
\begin{equation*}
\left.K_{1}=\left\langle\left\{\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{k_{1}}-1\right\}^{2}\right\rangle_{k_{2} k_{3}}, \tag{14}
\end{equation*}
$$

which approaches zero if there is no atomic overlap on the $a$ axis, and

$$
\begin{equation*}
\left.K_{12}=\left\langle\left\{\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{k_{1} k_{2}}-1\right\}^{2}\right\rangle_{k_{3}}, \tag{15}
\end{equation*}
$$

which approaches zero if there is no atomic overlap in the $\mathbf{c}$ projection. For comparison define

$$
\begin{equation*}
K=\left\langle\left\{\left|E_{\mathbf{k}}\right|^{2}-1\right\}^{2}\right\rangle_{\mathbf{k}} \tag{16}
\end{equation*}
$$

We shall show that $K_{1}$ and $K_{12}$ give an impression of the overlap in the projections on $a$ and along $\mathbf{c}$ respectively. An interpretation of $K$ has been given by Hauptman (1964). Here we shall show its connexion with $K_{1}$ and $K_{12}$.

If only two atoms $i$ and $j$ have the same $x$ coordinate then

$$
\begin{equation*}
\left.\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{k_{1}}=1+\frac{2 Z_{i} Z_{j}}{\sigma_{2}} \cos 2 \pi\left[k_{2}\left(y_{i}-y_{j}\right)+k_{3}\left(z_{i}-z_{j}\right)\right] \tag{17}
\end{equation*}
$$

and

$$
\begin{align*}
K_{1} & =\frac{4 Z_{i}^{2} Z_{j}^{2}}{\sigma_{2}^{2}}\left\langle\cos ^{2} 2 \pi\left[k_{2}\left(y_{i}-y_{j}\right)+k_{3}\left(z_{i}-z_{j}\right)\right]\right\rangle_{k_{2} k_{3}} \\
& =\frac{2 Z_{i}^{2} Z_{j}^{2}}{\sigma_{2}^{2}}\left(1+\delta_{2 y_{i} 2 y_{j}} \delta_{2 z_{i} z_{j}}\right), \tag{18}
\end{align*}
$$

where the subscripts $2 y_{i}$ etc. are shorthand notations for $2 y_{i}(\bmod 1)$ etc. In this case the minimum value of $K_{1}$ is $2 Z_{i}^{2} Z_{j}^{2} / \sigma_{2}^{2}$. It can be shown that every pair of atoms with the same $x$ coordinate gives a contribution to $K_{1}$ of at least $2 Z_{i}^{2} Z_{j}^{2} / \sigma_{2}^{2}$. If all atoms have the same $x$ coordinate then the minimum value of $K_{1}$ is

$$
\begin{equation*}
\sum_{i=1}^{N} \sum_{j=1}^{N} 2 Z_{i<j}^{2} Z_{j}^{2} / \sigma_{2}^{2}=1-\sigma_{4} / \sigma_{2}^{2} \tag{i}
\end{equation*}
$$

Next we consider the additional effect of a centre of symmetry. If two atoms $i$ and $j$, related by a centre of symmetry, have the same $x$ coordinate, this pair of atoms will give a contribution to $K_{1}$ of at least $2 Z_{i}^{4} / \sigma_{2}^{2}$. If two independent atoms $i$ and $j$ have the same $x$ coordinate not equal to zero or to a half then there are two pairs of atoms which contribute to $K_{1}$. These two pairs together give a contribution of at least $8 Z_{i}^{2} Z_{j}^{2} / \sigma_{2}^{2}$. If the $x$ coordinates of two independent atoms $i$ and $j$ are equal to zero (half) then the centrosymmetrically related atoms also have $x$ coordinates equal to zero (half). These four atoms together give a contribution to $K_{1}$ of at least $\left(2 Z_{i}^{4}+2 Z_{j}^{4}+16 Z_{i}^{2} Z_{j}^{2}\right) / \sigma_{2}^{2}$. If all atoms have the same $x$ coordinate, whence $x_{j}=0\left(\frac{1}{2}\right)$ for all $j$, the minimum value of $K_{1}$ can be shown to be

$$
\begin{equation*}
\left(\sum_{j=1}^{N / 2} 2 Z_{j}^{4}+\sum_{i=1}^{N / 2} \sum_{j=1}^{N / 2} 16 Z_{i<j}^{2} Z_{j}^{2}\right) / \sigma_{2}^{2}=2-3 \sigma_{4} / \sigma_{2}^{2} \tag{ii}
\end{equation*}
$$

The same results hold for $K_{12}$ if not only the $x$ coordinates, but also the corresponding $y$ coordinates are equal.

Hauptman (1964) found that the value of $K$ is equal to (i) for structures without coinciding interatomic vectors and to (ii) if there are only coinciding interatomic vectors as a consequence of a centre of symmetry. Clearly these values for $K$ can be interpreted as the result of the overlap of all atoms, i.e. the result of projecting on a point.

The contributions to $K_{1}$ and $K_{12}$ contain the squares of the $Z_{i} Z_{j}$. Therefore $K_{1}$ and $K_{12}$ are related to atomic overlap in projections of the squared structure. Also, they indicate the reliability of the $E_{\mathbf{h}}^{s}$ calculated with
the reduced Sayre-Hughes equations in the case that the conditions are not fulfilled.

## Different projection directions

In the preceding only the conditions of no overlap in the projection on $a$ and no overlap in the $\mathbf{c}$ projection have been considered. These conditions lead to the reduced Sayre-Hughes equations (5a) and ( $6 a$ ). Of course the absence of atomic overlap in other oneand two-dimensional projections leads to analogous results.
Define

$$
\begin{aligned}
& \mathbf{a}^{\prime}=u_{1} \mathbf{a}+u_{2} \mathbf{b}+u_{3} \mathbf{c}, \\
& \mathbf{b}^{\prime}=v_{1} \mathbf{a}+v_{2} \mathbf{b}+v_{3} \mathbf{c}, \\
& \mathbf{c}^{\prime}=w_{1} \mathbf{a}+w_{2} \mathbf{b}+w_{3} \mathbf{c},
\end{aligned}
$$

where $u_{1}, \ldots, w_{3}$ are integers so that $V^{\prime}{ }_{\text {cell }}=V_{\text {cel1 }}$. If no atoms overlap in the projection on $a^{\prime}$ then, analogous to (5a),

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{\substack{k_{1} \\ k_{1} v_{1}+k_{1}+v_{2} v_{2}+k_{3} v_{3}=n_{0} \\ k_{1} w_{1}+k_{2} w_{2}+k_{3} w_{3}=n_{0}}}^{n_{w}}, \tag{5b}
\end{equation*}
$$

where $n_{v}$ and $n_{w}$ are fixed integers [to be compared with $k_{2}$ and $k_{3}$ in (5a)]. If no atoms overlap in the $\mathbf{c}^{\prime}$ projection then, analogous to ( $6 a$ ),

$$
\begin{equation*}
E_{\mathbf{h}}^{s}=\frac{\sigma_{2}}{\sigma_{4}^{1 / 2}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{\mathbf{k}}{ }_{k_{1} w_{1}+k_{2} w_{2}+k_{3} w_{3}=n_{w}}, \tag{6b}
\end{equation*}
$$

where $n_{w}$ is a fixed integer [to be compared with $k_{3}$ in ( $6 a)$ ]. The corresponding overlap criteria are

$$
\left.\left.K_{1}=\left\langle\left\{\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{\mathbf{k}}^{k_{1} v_{1}+k_{2} v_{2}+k_{3} v_{3}=n_{v}} \begin{array}{c}
k_{1} w_{1}+k_{2} w_{2}+k_{3} w_{3}=n_{w} \tag{14b}
\end{array}\right)-1\right\}^{2}\right\rangle_{n_{0} \eta_{w}}
$$

and

$$
\begin{equation*}
\left.K_{12}=\left\langle\left\{\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{\mathbf{k}}^{k_{1} w_{1}+k_{2} w_{2}+k_{3} w_{3}=n_{1 v}}{ }^{-1}\right\}^{2}\right\rangle_{n_{w}} \tag{15b}
\end{equation*}
$$

respectively.

## The optimum value for $\boldsymbol{n}_{\boldsymbol{w}}$ in (6b)

Fig. 1 shows two limiting spheres I and II. The origin of II is shifted over the vector $\mathbf{h}$ with respect to the origin of I. Let the lattice point $\left(l_{1} l_{2} l_{3}\right)$ in I be connected with $E_{1}$ and in II with $E_{1}^{*}$. Then the coinciding points pertaining to $\mathbf{k}$ in I and to $-(\mathbf{h}-\mathbf{k})$ in II are associated with terms $E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}$ in the Sayre-Hughes equation. Only half of these coinciding points supply independent terms, because the lattice points pertaining to $\mathbf{k}$ in I and to - $(\mathbf{h}-\mathbf{k})$ in II correspond to the same terms as do the lattice points related to $\mathbf{h}-\mathbf{k}$ in I and to $-\mathbf{k}$ in II.

Coinciding lattice points lying on a plane correspond to terms in the reduced Sayre-Hughes equation ( $6 b$ ) [coinciding lattice points lying on a row correspond to terms in the reduced Sayre-Hughes equation (5b)]. It can be shown that the plane parallel to the $a^{\prime *} b^{\prime *}$ plane for which the surface inside both sphere I and sphere II
is as large as possible is obtained for $n_{w}=\frac{1}{2} q$, where $q=h_{1} w_{1}+h_{2} w_{2}+h_{3} w_{3}$. If $q$ is odd then this plane does not contain lattice points ( $n_{w}$ must be an integer). So the optimum value for $n_{w}$, giving in general the largest number of terms in ( $6 b$ ), is $n_{\text {wo }}=\frac{1}{2} q \pm \frac{1}{2}$ ( $q$ odd). Both values give the same set of terms $E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}$. If $q$ is even then for $n_{w}=\frac{1}{2} q$ only half the terms are independent. Consequently the optimum value for $n_{w}$ is in general $n_{w o}=\frac{1}{2} q \pm 1$ ( $q$ even). Again both values give the same set of terms $E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}$.
The determination of the optimum pair $\left(n_{v}, n_{w}\right)_{o}$ in (5b) is more intricate. However, the requirement of no atomic overlap on an axis will seldom be fulfilled and there is little practical need to pursue this aspect.

## A test

The dimethyl ester of meso-tartaric acid (Kroon \& Kanters, 1973), space group $P \overline{1}$, with six O and six C atoms in the asymmetric unit was used to test the theory in the preceding sections. From the atomic coor-


Fig. 1. Two limiting spheres I and II with an intersecting reciprocal-lattice layer. The origin of II is shifted over the vector $h$ with respect to the origin of $I$. The reciprocal-lattice vectors $\mathbf{k}$ and $-(\mathbf{h}-\mathbf{k})$ correspond to terms $E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}$ in the Sayre-Hughes equation.


Fig. 2. $K_{12}^{\prime}$ and $R_{12}$ values plotted against the length of the ( $w_{1}, w_{2}, w_{3}$ ) axis.


Fig. 3. The [001] projection (a) and the [100] projection (b). - Carbon atom; - Oxygen atom.
dinates 1868 normalized structure factors ( $\mathrm{Cu} K \alpha$ sphere) were calculated. Next, for 14 projection directions ( $w_{1}$, $w_{2}, w_{3}$ ) we calculated the overlap criterion

$$
\begin{equation*}
K_{12}^{\prime}=\frac{\sum_{n_{w}} W_{n_{w}}\left\{\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle_{\mathbf{k}}}{\sum_{n_{w}} W_{n_{w}}} \tag{14c}
\end{equation*}
$$

The weighting factor $W_{n_{w}}$ is equal to the number of terms $\left|E_{\mathbf{k}}\right|^{2}$ with $n_{w}$ fixed and copes with the different standard deviations for the $\left.\left.\langle | E_{\mathbf{k}}\right|^{2}\right\rangle$. For the corresponding reduced Sayre-Hughes equations having optimum values for $n_{w}$, we calculated the residual

$$
\begin{equation*}
R_{12}=\frac{\sum \left\lvert\, E_{\mathbf{h}}-\frac{\sigma_{2}^{3 / 2}}{\sigma_{3}}\left\langle E_{\mathbf{k}} E_{\mathbf{h}-\mathbf{k}}\right\rangle_{k_{1} w_{1}+k_{2} w_{2}+k_{3} w_{3}=n_{w o}}\right.}{\sum\left|E_{\mathbf{h}}\right|} \tag{19}
\end{equation*}
$$

where the summation extends over the largest 500 $\left|E_{\mathrm{h}}\right|$ 's.

In Fig. 2 the values of $K_{12}^{\prime}$ and $R_{12}$ are plotted against the length of the ( $w_{1}, w_{2}, w_{3}$ ) axis. It is seen that the general behaviour of $R_{12}$ is the same as that of $K_{12}^{\prime}$. Further it should be noted that the minimum of $R_{12}$ corresponds to the minimum of the overlap criterion. In this minimum $R_{12}$ is equal to 0.107 ; this value is not much larger than $0 \cdot 078$, which is obtained if in (19) no restrictions are imposed on $\mathbf{k}$.

The values for $K_{12}^{\prime}$ are related to atomic overlap in projections. Fig. 3 gives the projections along the
two shorter axes. Owing to the limited number of structure factors, point atoms are smeared out in a Fourier projection. Taking into account only the first diffraction ring (James, 1962), in such a way that the entire electron density of an atom is supposed to lie inside this ring, the standard deviation for the radius of an atom can be calculated to be $0.25 \AA(\mathrm{Cu} K \alpha$ sphere). This value is used for the atomic radii in Fig. 3. The [001] projection [Fig. 3(a)] contains two pairs of almost completely overlapping atoms. For the case of complete overlap they would give a contribution to the overlap criterion of at least $8 Z_{\mathbf{C}}^{2} Z_{\mathbf{O}}^{2} / \sigma_{2}^{2}=0.0128$ ( $Z_{\mathrm{C}}$ and $Z_{\mathrm{O}}$ are the atomic numbers of C and O respectively). The $K_{12}^{\prime}$ value for the [001] projection is equal to 0.0112 . Clearly this value is related to the two pairs of almost completely overlapping atoms. The minimum of $K_{12}^{\prime}$ (Fig. 2), equal to 0.0021 , corresponds to the [100] projection. From Fig. 3(b) it is seen that in this projection there is no atomic overlap.

It appears that for these examples the overlap criterion quite well reflects the actual atomic overlap in projection and that it gives an indication about the reliability of the corresponding reduced Sayre-Hughes equations.

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[^0]:    * A probabilistic approach leads to (4) containing conditional averages (Hauptman, 1970). Analogous results can be obtained for (5a) and (6a).

